



R18 Regulation

Subject code: 2E5BC

TKR COLLEGE OF ENGINEERING AND TECHNOLOGY

(Autonomous, Accredited by NAAC with 'A' Grade)

B.TechV Semester Regular Examinations, February 2021

Digital Signal Processing

(Electrical and Electronics Engineering)

Maximum Marks: 70

Date: 24.02.2021 Duration: 3 hours

- Note:**
1. This question paper contains two parts A and B.
 2. Part A is compulsory which carries 20 marks. Answer all questions in Part A.
 3. Part B consists of 5 Units. Answer any one full question from each unit.
 4. Each question carries 10 marks and may have a, b, c, d as sub questions.

Part-A

All the following questions carry equal marks

(10x2M=20 Marks)

- 1 What are linear shift invariant systems?
- 2 Find the Z transform of $x[n]$, if $x[n] = u[n]$.
- 3 State and prove periodicity property of DFT.
- 4 Determine the spectra or the Fourier Series Coefficient of the signal $x[n] = \cos \frac{\pi n}{3}$
- 5 List the differences between Butterworth and Chebyshev filters.
- 6 What are the limitations of Impulse invariant technique?
- 7 What is Gibbs's phenomenon associated with FIR filters?
- 8 What are the advantages of FIR filters as compared to IIR filters?
- 9 What is Zero input limit cycle oscillation?
- 10 What is Decimation?

Part-B

Answer All the following questions.

(10M X 5=50Marks)

- 11 For the system described by the difference equation
 $y[n] = -0.2y[n-1] + 0.48y[n-2] + x[n] + x[n-1]$, if $y[-1] = 1$ and $y[-2] = 0$
 - a) Determine system function and the impulse response.(5M)
 - b) Plot the poles and zeros and determine if the system is stable.(5M)

OR
- 12 For the system described by the difference equation
 $y[n] = -0.6y[n-1] + 0.4y[n-2]$
 - a) Find the step response.(5M)
 - b) Find the response to the input $x[n] = \left(\frac{1}{3}\right)^n u[n]$. (5M)
- 13 A, Find DFT of $x[n] = \{1, 2, -3, -1, -2, 0, 2, 3\}$ using Over-lap Save method (5M)
B. Explain Linear convolution property of DFT.(5M)

OR
- 14 A. Derive the algorithm for Decimation in Frequency radix-2 FFT. (5M)
B. Determine Inverse DFT of $X(K) = \{8, 1-j, 2+j, -j, 2, j, 2-j, 1+j\}$ using the above algorithm. (5M)

- 15 Using Bilinear transformation design a high pass filter, monotonic in passband and stop band with passband frequency of 1KHz at 2.4dB and down to 10dB at 330 Hz. The sampling frequency is 5KHz. (10M)

OR

- 16 Design a Chebyshev filter with the following specifications: maximum passband attenuation of 2.5dB at $\Omega_p = 20\text{rad/sec}$ and stopband attenuation of 30dB at $\Omega_s = 50\text{rad/sec}$. (10M)

- 17 Determine the coefficients of a linear phase FIR filter of length $M = 11$ which has a symmetric unit sample response and a frequency response that satisfies the conditions

$$H_r\left(\frac{2\pi k}{11}\right) = \begin{cases} 1, & \text{for } k = 0, 1, 2 \\ 0.4, & \text{for } k = 3 \\ 0, & \text{for } k = 4, 5 \end{cases}$$

using Frequency sampling method.

(10M)

OR

- 18 Design an FIR linear phase, digital filter approximating the ideal frequency response

$$H_d(\omega) = \begin{cases} 1, & \text{for } |\omega| \leq \frac{\pi}{6} \\ 0, & \text{for } \frac{\pi}{6} < |\omega| < \pi \end{cases}$$

for $M=13$, using Hamming window.

(10M)

- 19 Explain the characteristics of Limit cycle oscillations representing the system described by the difference equation $y[n] = 0.95y[n-1] + x[n]$. Determine the dead band of the filter. (10M)

OR

- 20 A. Explain multistage implementation of sampling rate conversion with block diagram. (5M)

B. Signal $x[n]$ is represented by $x[n] = \{0, 1, 2, 3, 4, 5, 6, 0, 1, 2, 3 \dots\}$.

i. Obtain decimated signal by a factor 2

ii. Obtain interpolated signal by a factor 2 (5M)